# Meeting 3

Date: 13 – Match – 2020

Agenda

* Introduction of the physical EZ10
* Status
* Modelling blockers
* Addressing questions about requirements and goals
* Status of RoadRunner licence request

## Attendance

* Professor Thomas Bräunl
* Oluwafemi Stephen Arowosafe
* Guangming Chen
* Yunzhuo Chen
* Gerardo Cisneros Mendoza

## Glossary of terms and acronyms

CARLA - Open-source simulator for autonomous driving research.

ROS - Robot Operating System. A flexible framework for writing robot software.  
EZ10 – Easy Mile Autonomous Shuttle

## Minutes

* The physical EZ10 has been introduced to the team.
* Change the visual image of the EZ10 model to look like the real one.
* We are going to get the maps license from Perth city temporary, probably just use it to get some help to ride it.
* Import models into Carla to run the models, and improve it later
* RoadRunner team has approved the request for an academic licence
* Complete the documentation for requirements and send the questions arisen to Professor Thomas.
* Some measures of the physical EZ10 have been done.

## Attachments

No attachments included.